MECA-H303 Vibration TP2

Dynamics of 1 degrees of freedom systems

Pinned bar vibrating

For the following mechanism:

- 1. Derive the equations of motion of the system using Newtonian dynamics.
- 2. Derive the equations of motion of the system using Lagrangian dynamics.
- 3. From the equation of motion, give the expression of the damped and undamped resonant frequency of the system.

Additional details for the exercise:

- Assume small angles of rotation
- Z represents an imposed displacement
- The moment of inertia of the bar is $I = (ml^2)/3$ when computed at its edge.
- The final answer should be expressed as a function of the coordinates on the schematic



Figure 1: Rigid bar pinned

Shaker on elastic beam

A shaker of mass m_s with two counter-rotating unbalanced masses m_e are mounted on a mass M rigidly attached in the middle of a beam of length L_b .

For this system:

- 1. Create the equivalent simplified mass-spring-damper system and applied force.
- 2. Derive the equations of motion of the system using Newtonian dynamics.
- 3. Derive the magnitude of the response as a funciton of the shaker's excitation frequency.

Additional details for the exercise:

- The stiffness of the beam k can be obtained from the table annexed to the exercise.
- Consider the beam pinned at each edge.



Figure 2: Shaker on elastic beam

BEAM TYPE	SLOPE AT ENDS	DEFLECTION AT ANY SECTION IN TERMS OF x	MAXIMUM AND CENTER DEFLECTION				
6. Beam Simply Supported at Ends – Concentrated load <i>P</i> at the center							
$\begin{array}{c c} \theta_1 & P & \theta_2 & X \\ \hline & & & \\ y & & & \\ y & & & \\ \end{array} \xrightarrow{\begin{array}{c} \theta_1 \\ \end{array}} \delta_{max} \end{array}$	$\theta_1 = \theta_2 = \frac{Pl^2}{16EI}$	$y = \frac{Px}{12EI} \left(\frac{3l^2}{4} - x^2\right)$ for $0 < x < \frac{l}{2}$	$\delta_{\max} = \frac{Pl^3}{48EI}$				
7. Beam Simply Supported at Ends – Concentrated load P at any point							
$\begin{array}{c} & & P \\ \hline 0, y \\ \hline y \\ y \\ \hline y \\ I \\ \hline \end{array} \begin{array}{c} & & \\ & \\ & \\ & \\ & \\ & \\ & \\ & \\ & \\ $	$\theta_1 = \frac{Pb(l^2 - b^2)}{6lEI}$ $\theta_2 = \frac{Pab(2l - b)}{6lEI}$	$y = \frac{Pbx}{6lEI} \left(l^2 - x^2 - b^2 \right) \text{ for } 0 < x < a$ $y = \frac{Pb}{6lEI} \left[\frac{l}{b} \left(x - a \right)^3 + \left(l^2 - b^2 \right) x - x^3 \right]$ for $a < x < l$	$\delta_{\max} = \frac{Pb\left(l^2 - b^2\right)^{3/2}}{9\sqrt{3}lEI} \text{ at } x = \sqrt{\left(l^2 - b^2\right)/3}$ $\delta = \frac{Pb}{48EI} \left(3l^2 - 4b^2\right) \text{ at the center, if } a > b$				

Figure	3:	Beam	rigidity	table
I ISUIC	. .	Doam	ingrand,	000010