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# **VIB : MDOF systems**

Number of participants: 34





### The mode shapes and eigenfrequencies of a system are **17 correct answers** 4. determined by (K and M are the stiffness and mass out of 21 respondents matrices) Calculating the eigenvalues of the 2 votes 10% stiffness matrix K of the system solving a generalized eigenvalue problem 17 votes 81% of the type (K-w^2M) $\{Phi\} = 0$ Calculating the eigenvalues of the mass 1 vote 5% matrix M of the system Calulating w=K/M 1 vote 5%

### 5. If a system has n degrees of freedom, it has

### 18 correct answers

out of 23 respondents

2n natural frequencies	9%	2 votes
n natural frequencies	78%	18 votes
(n + the number of excitations) natural frequencies	9%	2 votes
it depends on the type of system	4%	1 vote

# 6. How many Degrees of freedom would this real world structure have?

### 21 respondents







### 8. The mode shapes are orthogonal with respect to the **12 correct answers** out of 28 respondents stiffness matrix 82% 23 votes mass matrix 54% 15 votes damping matrix 4 votes 14% The interest of projecting the equations of motion in the **19 correct answers** 9. modal domain is to: out of 25 respondents reduce the number of equations to solve 3 votes 12% decouple the equations of motion and 76% 19 votes facilitate solving them

12%

work with physical quantities for a better understanding of the system's behavior

3 votes





## 11. Where is the anti-resonance of the 2 DOFs system on this graph ?

26 respondents



19

**12.** An anti-resonance happens when

20 correct answers

out of 27 respondents





## **15.** How many mode shapes and eigenfrequencies does this building simplified model have ?

**13 correct answers** out of 15 respondents



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### If this system is excited with an harmonic force applied 16. to the bottom mass, whose frequency is close to the first natural frequency, the motion will correspond to

**8 correct answers** out of 21 respondents



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If this system is excited with an harmonic force applied
to the bottom mass, whose frequency is the average of the first and second natural frequencies of the system, the motion will correspond to

**22 correct answers** out of 26 respondents

22 votes



85%

A combination of the two mode shapes

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### Why is the damping coefficient higher for the second 18. mode than for the first mode for the damped two dofs system treated in the examples of the course ?

4 respondents



The x2 value in the wn2 frecuency is lower than in wn1

Sqrt3

Because  $\sqrt{3}$ 

There are more damping points affecting the second mode

This is the impulse response of a damped two dofs
system. Is it possible to extract the information on the first natural frequency and damping from this curve in a simple way ?

**12 correct answers** out of 23 respondents



No answers in this question

-

### This is the impulse response of a damped two dofs 21. system. Is it possible to extract the information on the second natural frequency and damping from this curve ?

22 correct answers out of 23 respondents



No, impulse responses show only the response from one mode at a time

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### This is the time domain response of a damped 2 DOFs 22. system under sine sweep excitation. Where do you see the resonances on the time domain response ?

15 respondents

50

**12 correct answers** 

### Sine sweep excitation



23. When a system is excited by its base, it is easier to write 12 correct answers out of 24 respondents out of 24 respondents as relative displacement between the eighbouring DOFS 10 votes as relative displacement between the base and each DOF. 12 votes 12 votes 12 votes 12 votes 12 votes 13 votes 14 votes 14 votes 150% 14 votes 14 votes 150% 15 votes 14 votes 15 votes 14 votes 15 votes 14 votes 15 votes

24. the case of an applied force which is
 proportional to the applied acceleration
 inversely proportional to the applied acceleration
 proportional to the applied displacement
 21%

When doing so, the equation of motion is equivalent to